1	A quantitative biophysical principle to explain the 3D cellular
2	connectivity in curved epithelia
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#### 1 SUMMARY

2 Epithelial cell organization and the mechanical stability of tissues are closely related. 3 In this context, it has been recently shown that packing optimization in 4 bended/folded epithelia is achieved by a surface tension energy minimization 5 mechanism that leads to a novel cellular shape: the scutoid. However, further cellular 6 and tissue level implications of this new developmental paradigm remain unknown. 7 Here we focus on the relationship between this complex cellular shape and the 8 connectivity between cells. We address this problem using a combination of 9 computational, experimental, and biophysical approaches in tubular epithelia. In 10 particular, we examine how energy drivers affect the three-dimensional packing of these tissues. We challenge our biophysical model by reducing the cell adhesion in 11 epithelial cells. As a result, we observed an increment on the cell apico-basal 12 intercalation propensity that correlated with a decrease of the energy barrier 13 14 necessary to connect with new cells. We conclude that tubular epithelia satisfy a 15 quantitative biophysical principle, that links tissue geometry and energetics with the 16 average cellular connectivity.

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#### 19 **KEYWORDS**

Tissue/Cellular Biophysics, Computational geometry, Developmental Systems 20 Biology, Mathematical/Biophysical modeling, Bioimage Analysis

22

#### **1** INTRODUCTION

2 During the last decades much progress has been achieved in the understanding of 3 the emergence of self-organization in tissues. This problem has been addressed from 4 the viewpoint of energetics considerations (Alt et al., 2017; Canela-Xandri et al., 5 2011; Fletcher et al., 2014; Misra et al., 2017; Nelson et al., 2005; Siedlik et al., 2017; 6 Sugimura et al., 2016; Trepat et al., 2009), material-like properties (Bi et al., 2015; 7 Campàs et al., 2014; Latorre et al., 2018; Mongera et al., 2018; Pérez-González et al., 8 2019; Yang et al., 2017), and the analysis of the cellular packing (Curran et al., 2017; Farhadifar et al., 2007; Gibson et al., 2006; Gibson et al., 2011; Gómez et al., 2021; 9 10 Honda, 1978; Lewis, 1928; Mao et al., 2013; Sanchez-Gutierrez et al., 2016; 11 Thompson, 1945). As for the latter, the analysis of epithelial surfaces as tessellations 12 of convex polygons has revealed mathematical and physical principles with biological 13 consequences. One well-known example are the implications of the celebrated Euler's formula,  $V - E + F = \chi$  (STAR Methods) (Euler, 1767). This formula implies 14 15 that cells in packed tissues have, on average, six neighbors (i.e., the average cellular connectivity on a surface reads  $\langle n_{2D} \rangle = 6$ ) (Reinhardt, 1918; Wetzel, 1926). This 16 principle has biological consequences, for example, the degree of cellular 17 18 connectivity regulates the strength of the cell-cell juxtracrine signaling (Guignard et 19 al., 2020; Sharma et al., 2019; Tung et al., 2012).

20 For a long time, the validity of this mathematical concept (i.e., each cell, on average, 21 connects with six neighboring cells) has been assumed in three dimensions (3D):  $\langle n_{2D} \rangle = 6 \implies \langle n_{3D} \rangle = 6$ . Such an assumption is rooted in the common idealization 22 23 of epithelial cells as regular prismatic solids in either planar or bended epithelia. 24 However, the recent discovery of more complex cellular shapes in epithelia, i.e., 25 scutoids, that achieve an efficient 3D tissue packing has set a new paradigm that has 26 not been yet fully explored (Box A) (Gómez-Gálvez et al., 2018; Mughal et al., 2018; 27 Rupprecht et al., 2017). Scutoidal cellular shapes are the result of intercalations 28 among cells along the apico-basal axis (Box A-C and Fig. 1A). This phenomenon is 29 then a spatial version of the so-called T1 transitions that produce rearrangements of 30 neighboring cells in the plane as a function of time in numerous developmental 31 processes (Box B) (Bertet et al., 2004; Irvine and Wieschaus, 1994; Spencer et al.,

1 2017). Importantly, scutoids imply necessarily changes in the neighboring 2 relationship between cells in a 3D spatial context and, consequently, modify the 3 connectivity properties of cells (Box C). Still, the analysis of tissue organization in 3D and the corresponding biophysical insight have been hindered by the technical 4 5 difficulties to accurately segment and 3D-reconstruct cells, especially in curved 6 tissues. In addition, very few computational models account for the presence of apico-basal transitions to investigate 3D self-organization in tissues (Gómez-Gálvez et 7 al., 2018; Ioannou et al., 2020; Mughal et al., 2018; Okuda et al., 2019; Rupprecht et 8 9 al., 2017). Moreover, from an energetics viewpoint, while the appearance of scutoids can be explained by a minimal model based on a surface/line tension minimization 10 mechanism (Gómez-Gálvez et al., 2018; Mughal et al., 2018; Okuda et al., 2019; 11 12 Rupprecht et al., 2017), the role played by additional energetic contributions to 13 modulate the frequency of apico-basal intercalations is unknown.

14 The analysis of 3D packing is in turn utterly relevant in cubic and columnar 15 monolayer tubular epithelia, where scutoids appear more frequently (Gómez-Gálvez 16 et al., 2018; Gómez et al., 2021; Iruela-Arispe and Beitel, 2013; Sanchez-Corrales et 17 al., 2018). Epithelial tubes are in fact the primary developmental structures in all 18 organisms with bilateral symmetry (Gilbert and Barresi, 2013), and tubulogenesis is fundamental in a broad variety of key developmental processes, including 19 20 gastrulation and neurulation (Colas and Schoenwolf, 2001; Iruela-Arispe and Beitel, 21 2013; Leptin and Grunewald, 1990; Nelson, 2009; Pilot and Lecuit, 2005; Röper, 2018; 22 Swanson and Beitel, 2006). Furthermore, epithelial tubes are the essential functional 23 unit of many mammalian organs, including glands, components of the digestive 24 apparatus, lungs, and kidney (Huebner and Ewald, 2014).

Here, we study the packing and the 3D cellular connectivity properties of epithelial tubes. We analyze the effect of different energetic contributions to modulate the frequency of apico-basal intercalations; demonstrate that the presence of scutoids implies a breakdown of the principle  $\langle n_{3D} \rangle = 6$ ; and reveal a quantitative biophysical principle that links the 3D cellular connectivity, energetics, and geometrical descriptors (e.g., tissue curvature/thickness). Our findings are supported by i) a computational model that realistically renders the 3D cellular organization of tubular

epithelia (including the appearance of scutoids); ii) experimental data of wildtype (wt) and mutant epithelial tubes (*Drosophila*'s salivary gland) whose 3D cellular structure has been accurately characterized by means of a computer-aided image analysis pipeline. And iii), a biophysical model, supported by mathematical calculations, that connects the tissue energetics with the 3D organization of epithelial tubes.

7

8 **RESULTS** 

## 9 The Voronoi computational tubular model supports a relationship between energy 10 profiles and the intercalation propensity

11 To understand how the geometry of tubular epithelia and different energy 12 contributions affect the 3D cellular packing and connectivity of these tissues, we designed and implemented a computational epithelial model that follows the 13 14 principles of Voronoi tessellations (Box D, E) (Gómez-Gálvez et al., 2018). In brief, we 15 generated 3D models of epithelial tubes by populating with seeds the apical surface, 16  $\Sigma_a$  (light blue points in **Fig. 1B**) and implementing normal projections of those seeds 17 up to the basal surface,  $\Sigma_b$  (dark blue points in **Fig. 1B**). Each seed and its projection 18 corresponded to an individual cell of a tube. At each surface section  $\Sigma$  (from apical to basal) a 2D Voronoi diagram was performed, and the collection of those tessellations 19 20 rendered the 3D cellular geometry of cells (see details in STAR Methods). We point out that we do not implement any temporal dynamics to the seeds. Thus, our 21 22 computational model is suited to static epithelial configurations as the ones 23 experimentally reported herein (see below).

24 Epithelial tubes appear in nature with very different thicknesses and cellular 25 arrangements. In order to explore how these features influence the 3D packing 26 properties of tubular epithelia we built diverse in silico Voronoi tubes. First, to 27 investigate the effect of tissue thickness we computed Voronoi tubes with different 28 surface ratios  $s = R/R_a$  (R and  $R_a$  being the radial coordinate of the tube and the 29 apical radius respectively, Fig. 1C, D). We used s-steps of 0.5 up to s = 10, so we 30 were able to explore 19 different values of the basal radius,  $R_b$  (Fig. 1D). Second, we 31 generated 10 different configurations in terms of the disorder level of the spatial

1 positions of the cellular seeds on the apical surface and the corresponding Voronoi 2 tessellations (V1 to V10, Fig. 1D). To that end, we used a fully random Voronoi 3 tessellation, i.e., randomized positions of cellular seeds, as the most disordered pattern (V1). That configuration was made progressively more uniform (i.e., spatially 4 ordered) after nine successive iterations of the homogenizing Lloyd's algorithm (Box 5 6 E and STAR Methods) (Fig. 1D). The resulting set of 10 different cellular arrangements (V1 to V10) with increasing order properties conforms a Centroidal 7 8 Voronoi Tessellation (CVT) scale that has been proved useful to analyze the effect of the topological organization of tissues and to simulate different tissues and/or 9 pathological conditions (Sanchez-Gutierrez et al., 2016; Vicente-Munuera et al., 10 2020). We used the CVT scale to investigate how the average number of apico-basal 11 12 intercalations per cell,  $\langle i \rangle$ , changes as a function of the apico-basal coordinate, s, and 13 the disorder level (Fig. 1D). As previously reported, we found that the number of 14 apico-basal transitions (Fig. 1D) and scutoids (Fig. S1) increased with s (Gómez-15 Gálvez et al., 2018). As for the effect of the disorder level, we found that only in the case of fully disordered tubes (i.e., V1: random case), and for low values of s, there 16 17 are more intercalations, whereas for the rest of cases we observed that  $\langle i \rangle$  is fairly 18 independent of the CVT scale (Fig. 1D).

19 Energy contributions can be linked to geometric features of the shapes of epithelial 20 cells (Alt et al., 2017), see Box F-H. We used the set of Voronoi tubes (V1 to V10) to explore surface tension, elasticity, and apical contractility energies, since these 21 22 energy contributions have been shown to play key roles in the organization of 23 epithelia (Alt et al., 2017; Farhadifar et al., 2007). As a first step, we estimated the 24 average cellular energy profiles as a function of s in the computational tubular model 25 (Fig. 1E-G). The average surface tension energy (Box F) is related to the average 26 lateral area of the cells,  $\langle A \rangle$ , and therefore increase with the surface ratio, s. Our 27 results revealed that  $\langle A \rangle$  is seemingly independent of the CVT scale (Fig. 1E). 28 Consequently, the average cell surface tension energy profile does not depend on the level of the topological disorder. The contractile energy (**Box G**) is related to the 29 30 average and the variance of the apical perimeter,  $L_{i}$  (Gilbert and Barresi, 2013; Farhadifar et al., 2007) therefore it does not depend on the surface ratio, s. The 31

1 Voronoi model revealed that  $\langle L \rangle$  is CVT independent, but the apical perimeter 2 fluctuations decrease as the CVT scale increases (**Fig. 1F**). Finally, the average cell 3 elastic energy (Gelbart et al., 2012; Odell et al., 1981) depends on the average and 4 the variance of the cellular volume (**Box H**). Since the average cell volume  $\langle V \rangle$  is, by 5 construction, independent of the CVT scale (**STAR Methods**), the average cellular 6 elastic energy increases with the cellular volume fluctuations, that in turn decrease 7 with the CVT scale (**Fig. 1G**).

8 In order to evaluate how the appearance of scutoids is modulated by these energy 9 contributions for different values of the tissue thickness, we computed the crosscorrelation functions, C(s), between the average cellular energy profiles,  $\langle E_z \rangle$  (Z 10 being A or V, i.e., surface tension or elastic terms), and the average number of apico-11 12 basal intercalations,  $\langle i \rangle$  (Fig. 1H and STAR Methods). The cross-correlation measures the similarity between two signals as a function of the displacement (or lag) of one 13 14 signal relative to the other. In our case the displacement/lag refers to the apico-basal coordinate,  $s_{i}$  and consequently we inquire into the possibility that energetic 15 16 contributions either precede or follow the appearance of apico-basal intercalations. 17 Our results indicate that maximum correlations are obtained at zero lag 18 independently of the disorder level and that the appearance of scutoids correlates 19 more significantly with the surface tension energy profile than with the elastic 20 energy: 95% vs. 80% respectively. The latter is in agreement with previous studies 21 that have shown that surface tension energy minimization is the main cause 22 underlying the appearance of scutoids (Gómez-Gálvez et al., 2018; Gómez et al., 23 2021; Mughal et al., 2018). Also, when assessing the extra effect of the energy input due to the apical contractility term to the surface tension energy,  $\langle E_A \rangle + \langle E_L \rangle$ , we 24 25 found that it increases the correlation between energy profile and the number of 26 intercalations up to 98%, but it does not lead to any change in the correlation due to elastic terms,  $\langle E_V \rangle + \langle E_L \rangle$  (Fig. 1H). 27

We further examined the cross-correlation between the gradient of cellular intercalations along the apico-basal axis,  $\partial_s \langle i \rangle = \partial \langle i \rangle / \partial s$ , and the gradient of the energy,  $\partial_s \langle E_Z \rangle$ . In this way, we evaluated the level of correspondence between the variation of the number of intercalations and the changes of the energy as a function

of the radial coordinate, s. We found that, independently of the CVT scale,  $\partial_s \langle i \rangle$ correlates slightly stronger with changes in the surface tension energy,  $\partial_s \langle E_A \rangle$ , than with changes of the elastic contribution,  $\partial_s \langle E_V \rangle$ : ~80% versus ~75% respectively at optimal lag (**Fig. 1**I). Interestingly,  $\partial_s \langle i \rangle$  lags behind  $\partial_s \langle E_Z \rangle$ , i.e., the optimal lag for which C(s) is the largest is located at s > 0. Therefore, energy variations along the apico-basal axis seem to precede changes in the number of intercalations that, in turn, suggests an instructive role of the former over the latter.

8 Summing up, the Voronoi tubular model supports the idea that surface tension 9 energy is the more relevant contribution regulating the appearance of apico-basal 10 intercalations, and suggests that elastic terms play a role, yet less important than 11 surface tension, for modulating the intercalation propensity (see **Discussion**).

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### 13 The Voronoi tubular model suggests a link between 3D tissue packing and energy14 cues

15 To link quantitatively energy traits and 3D packing, we implemented a benchmark 16 able to simultaneously reveal the existence of apico-basal intercalations (scutoids) 17 and the polygonal distribution of cells at the apical and the basal surfaces. To that end, we computed the probability that cells change their polygonal class between the 18 19 apical and basal surfaces. Thus, the components (i.e., bins) of this distribution along the diagonal account for cells that have the same polygonal class at apical and basal 20 21 surfaces, whereas the spreading away from the diagonal ensures the existence of 22 scutoids and, consequently, changes in the cellular 3D connectivity (Fig. 2A and STAR 23 Methods). Our data revealed that, regardless of the value of the tissue thickness (and 24 the CVT scale), the dominant apical-basal polygonal class corresponds to cells with six 25 neighbors (Fig. 2A). As the tissue thickness,  $s_b = R_b/R_a$ , increases, more scutoidal 26 shapes with a distinct number of neighbors in apical and basal surfaces appeared. 27 This feature was revealed by the increasing value of the spreading away from the diagonal,  $\eta^2$  (STAR Methods and Table S1). In that regard, in agreement with the 28 29 results shown in **Fig. 1D-G**, our data indicates that  $\eta^2$  increases with the tissue thickness and decreases with the CVT scale (Fig. 2B). Also, the cross-correlation 30 31 analysis between the spreading coefficient and energy profiles agrees with Fig. 1H

1 and reveals that independently of the CVT scale the neighbor exchanges correlate 2 more strongly with the surface tension energy profile than with the elastic 3 contribution: 90% vs. 70% at zero (optimal) lag (Fig. 2C). Furthermore, we computed 4 the average number of total contacts between cells (i.e., the average 3D cellular connectivity),  $(n_{3D})$ , as a function of the surface ratio (i.e., the radial coordinate) and 5 6 the Voronoi class (i.e., the level of cellular disorder in the tissue) (Fig. S1). Our data indicated, that cells, on average, are connected to more than six cells, i.e.,  $\langle n_{3D} \rangle > 6$ , 7 8 and the results are quantitatively consistent with a mathematical derivation that 9 shows that  $\langle n_{3D} \rangle$  is linearly proportional to the number of apico-basal intercalations  $\langle i \rangle$ :  $\langle n_{3D} \rangle = 6 + \langle i \rangle / 2$  (STAR Methods and Fig. S1). 10

11

#### 12 The Voronoi tubular model recapitulates the properties of *in vivo* epithelial tubes

13 In order to compare the results obtained in our Voronoi computational tubular models against the properties found in real tissues, we implemented a 14 methodological pipeline that combines several image analysis techniques to 15 16 accurately reconstruct the 3D shapes of cells of in vivo epithelial tubes (Arganda-17 Carreras et al., 2017; Franco-Barranco et al., 2021; Machado et al., 2019) (STAR 18 Methods). We used the Drosophila larval salivary gland, a cubic monolayer epithelium, as a model due to its ideal characteristics to study complex tubular 19 20 developmental structures (Girdler and Roper, 2014) (Fig. 3A). Also, cellular growth 21 and division, as well as possible global tissue deformation processes, do not occur in 22 the Drosophila's salivary gland at the developmental stage of our observations (i.e. 23 the tissue is static); a fact that enables the comparison with the Voronoi 24 computational model.

We determined the average basal surface ratio (thickness) of the salivary glands,  $\langle s_b \rangle = 8.5 \pm 1.1$ , the average percentage of scutoids,  $72 \pm 12\%$ , the average 3D connectivity,  $\langle n_{3D}(s_b) \rangle = 6.6 \pm 0.2$ , and the average number of apico-basal intercalations per cell,  $\langle i(s_b) \rangle = 1.2 \pm 0.3$ , thus confirming *in vivo* the validity of the formula  $\langle n_{3D} \rangle = 6 + \langle i \rangle/2$  (STAR Methods and Fig. S1). We also calculated the spreading coefficient of the 3D connectivity,  $\eta^2 = 1.2 \cdot 10^{-2}$ , (Fig. 3B), and the 2D polygonal distributions in the apical and basal surfaces (Fig. S2). Interestingly, we

observed a small, but significant, increase of the number of hexagons on the basal
 surface of the wt glands (see Fig. S2, Table S1).

3 Further, in order to derive how energy contributions change as a function of the 4 apico-basal coordinate, s, we implemented an algorithm that obtains the concentric radial sections of in vivo tubes from apical to basal (Yang et al., 2019) (STAR 5 6 **Methods**). These sections were used to quantify as a function of the surface ratio,  $s_i$ 7 the number of apico-basal intercalations,  $\langle i(s) \rangle$ , the average lateral area,  $\langle A(s) \rangle$ , and the cellular volume fluctuations,  $\sigma_V^2(s)$  (Fig. 3C). Similarly to the procedure that we 8 9 implemented in the Voronoi tubular model (Fig. 1H, I), we used these in vivo data to 10 perform a cross-correlation analysis between  $\langle i \rangle$  and the energy contributions  $\langle E_z \rangle$ (Z being A or V, i.e., surface tension or elastic terms). The results indicated that in 11 12 vivo intercalations also correlate stronger with surface tension energy contributions 13 than with elastic terms: ~98% vs. ~90% at zero (optimal) lag (Fig. 3D). We also found 14 that in this case, by including the extra contribution from the apical contractile energy to the surface tension energy, i.e.  $\langle E_A \rangle + \langle E_L \rangle$ , slightly decreases the 15 16 correlation down to ~95% (optimal lag) but does not modify that of the elastic term, 17 i.e.  $\langle E_V \rangle + \langle E_L \rangle$  (Fig. 3D). As for the cross-correlation between  $\partial_s \langle i \rangle$  and  $\partial_s \langle E_Z \rangle$ , we 18 also found that in *in vivo* tubes it is more significant for the case of the surface 19 tension energy, ~80%, than for the elastic contribution, ~70%. In addition, we also 20 observed a positive lag for  $\partial_s \langle E_V \rangle$  that suggests an instructive role of elastic energy 21 variations towards changes in the number of apico-basal intercalations (Fig. 3E).

22 Subsequently, we sampled the Voronoi tubular model in terms of the disorder 23 configuration (CVT scale) and the value of the thickness,  $s_b$ , that leads to a tube that 24 represents the aforementioned properties observed in vivo. We found that the V8 in 25 silico model with  $s_b = 1.75$  displayed a scutoidal prevalence,  $79 \pm 5\%$ , average 26 number of 3D neighbors,  $6.72 \pm 0.08$ , average number of apico-basal intercalations per cell,  $1.4 \pm 0.1$ , and value of the 3D histogram spreading,  $\eta^2 = 1.4 \cdot 10^{-2}$ , 27 28 comparable to those found in in vivo tubes (Fig. S3). Further, the 2D polygonal 29 distributions in the apical and basal surfaces of the V8 model ( $s_b = 1.75$ ) were found 30 to be similar and in agreement with those found in wt salivary glands (Fig. S2 and 31 Table S1). We also observed that the increment apico-basal transitions by means of a 1 larger surface ratio ( $s_b = 10$ ) leads to an increase of topological disorder (larger 2 variance of cell sidedness, see Fig. S2 and Table S1); a phenomenon that is similar to 3 that observed in T1-transitions (Blankenship et al., 2006; Zallen and Zallen, 2004). 4 Finally, we implemented the cross-correlation analyses between intercalations and 5 energy contributions in the V8 model ( $s_b = 1.75$ ). We obtained similar features as 6 those obtained *in vivo*, including the suggested instructive role of elastic energy 7 variations towards changes in the number of apico-basal intercalations (Fig. S3). 8 Altogether, we concluded that the V8 model ( $s_b = 1.75$ ) reproduces the 2D and 3D 9 packing properties of the *Drosophila*'s larval salivary glands.

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# A biophysical model explains the cellular connectivity observed in *in silico* and *in vivo* tubular epithelia

13 In order to explain how the number of 3D neighbors of a cell (i.e., the cellular 14 connectivity) changes as a function of the apico-basal coordinate, we developed a 15 biophysical model. The model is based on a Kolmogorov rate equation and accounts 16 for the probability of cells to increase their 3D connectivity as the radial coordinate 17 along the apico-basal axis changes from s to s + ds (**Fig. 4A, B** and **STAR Methods**):

18 
$$\frac{dP_m(s)}{ds} = P_{m-1}(s)r_{m-1,m} - P_m(s)r_{m,m+1}$$
(1)

19 This equation determines, as a function of *s*, the set of probabilities  $\{P_m(s)\} = P_3(s), P_4(s), \dots, P_{N_{max}}(s)$ , i.e., the fractions of cells with a given number, *m*, of 3D 21 neighbors such that  $\sum_m P_m(s) = 1$ . Thus, the average 3D cellular connectivity (i.e., 22 the average number of 3D neighbors per cell) as a function of *s* reads  $\langle n_{3D}(s) \rangle =$ 23  $\langle m \rangle = \sum_m m P_m(s)$ .

In Eq. (1),  $r_{m,m+1}$  accounts for the transition "rate" at which 3D are gained, i.e., the probability per unit of *s* to increase the cellular connectivity by one cell. By drawing parallels between apico-basal intercalations and planar T1 transitions (Bi et al., 2014; Gómez-Gálvez et al., 2018; Sanchez-Corrales et al., 2018) we assumed, following the Eyring model (Eyring, 1935), that cells need to overcome an energy barrier,  $\Delta E_m(s)$ , to gain a new 3D neighbor, that is,  $r_{m,m+1} \sim e^{-\Delta E_m(s)}$  (Fig. 4A, B). Our experimental, computational, and analytical results (see STAR Methods and Figs. S4, S5) support

the idea that  $r_{m,m+1} = \alpha (N_{max} - m)e^{-m\beta(s)}$ , where  $\alpha$  is a 'bare' transition "rate", 1  $\beta(s)$  accounts for the energy cost required to gain one 3D neighbor at a given 2 3 position of the apico-basal coordinate, s, and  $N_{max}$  is the maximum possible 3D cellular connectivity for a cell (i.e., if  $m = N_{max}$  then  $r_{m,m+1} = 0$ ) (STAR Methods). 4 This model predicts a logistic-like growth of the cellular connectivity (STAR Methods). 5 6 In order to assess the validity of our model we implemented a fitting/optimization 7 procedure that provides the value of the model parameters that minimize the error 8 in the fitting of the curve  $\langle n_{3D}(s) \rangle$  (STAR Methods). Our results show an excellent 9 agreement for all values of the CVT scale (Fig. S6, Table S1), the computational 10 tubular model that represents the best in vivo data, i.e. V8 ( $s_b = 1.75$ ) (Fig. 4C), and 11 the wt salivary glands (Fig. 4D). We further assessed the goodness of the biophysical 12 model by predicting accurately the 3D neighbor's distribution as a function of the apico-basal coordinate,  $\{P_m(s)\}$  (Fig. 4C, D, Fig. S6). 13

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## Genetic perturbations modify the 3D cellular connectivity properties of epithelial tubes

17 Our analyses suggest that surface tension is the energy contribution that affects the 18 propensity of apico-basal intercalations the most. Surface tension energy originates 19 in adhesion-mediated interactions between cells that ultimately modulate the 20 magnitude of cell-cell contacts. Following these ideas, we explored the role of cell-21 cell adhesion by experimentally reducing the amount of the E-cadherin (E-cadh). For 22 this aim, we overexpressed a UAS-RNAi line specific for the shotgun (shq) gene on the 23 developing Drosophila salivary gland (Brand and Perrimon, 1993; Hammond et al., 24 2000; Tepass et al., 1996) (STAR Methods). We compared the E-cadh antibody 25 fluorescence profiles in wt and the mutant glands ( $\Delta$ Ecad) and confirmed the 26 reduction of E-cadh levels in the latter (**Fig. S7**). The cells in the  $\Delta$ Ecad glands bulged 27 at the basal surface and were smaller than the wt cells (Fig. 5A, Table S1, Fig. S7). We 28 processed these glands to extract their 3D cellular connectivity features and average 29 energy profiles (STAR Methods and Table S1). We determined the effective average basal surface ratio (STAR Methods) of the mutant salivary glands  $\langle s_b \rangle = 7.4 \pm 0.8$ , 30 31 the average percentage of scutoids,  $65 \pm 14\%$ , the average 3D connectivity,

1  $6.5 \pm 0.2$ , and the average number of apico-basal intercalations per cell,  $1.1 \pm 0.4$ , (Table S1, Fig. S7). These values confirm the validity of the formula  $\langle n_{3D} \rangle = 6 +$ 2 3  $\langle i \rangle / 2$  in this genetic background too. Also, the cross-correlation analysis revealed 4 that the surface tension energy remained as the main energy contribution (Fig. S8). 5 Thus,  $\Delta$ Ecad and wt glands reached the same 3D connectivity although the effective 6 surface ratio of the former was smaller (Table S1). These results suggest that a 7 decrease in the cellular adhesion facilitates the emergence of apico-basal 8 intercalations.

9

### 10 The reduction of cellular adhesion decreases the activation energy required to 11 produce apico-basal intercalations

12 The fitting/optimization procedure of the mutant data showed, as in the case of the 13 wt phenotype and the in silico tubes, an excellent agreement (Fig. 5B) that allowed 14 us to estimate the energy-related parameters as summarized by  $\alpha$  and  $\beta(s)$  (Fig. 5C 15 and **Table S1**). The estimation of  $\alpha$  and  $\beta(s)$  in wt and mutant tubes indicated that the energy required to gain an additional neighbor,  $\beta(s)$ , is larger in *in vivo* tubes 16 17 than in the computational model independently of the CVT scale (Fig. 5C, Fig. S9, Table S1), see Discussion. Finally, the results obtained from the analysis of the 18 19 mutant glands confirmed that a decrease in the cellular adhesion facilitates the emergence of apico-basal intercalations since the activation energy gets reduced in 20 21 the  $\Delta$ Ecad phenotype when compared to the wt case (Fig. 5B and 5C, and Table S1). 22 In particular, in the mutant case, the curve that describes the energetic cost to gain 23 new neighbors as a function of the apico-basal coordinate,  $\beta(s)$ , lies below the curve 24 of the wt background (Fig. 5C) and we found that the average energy cost,  $\bar{\beta}$  (STAR **Methods**), is ~43% larger in the wt case:  $\bar{\beta}_{\Delta \text{Ecad}} = 0.46$  and  $\bar{\beta}_{\text{wt}} = 0.65$ . Altogether, 25 26 when we challenged the biophysical model with the perturbation experiment, we 27 obtained the expected results: smaller cellular adhesion leads to a smaller energetic 28 cost to gain new neighbors.

29

**30 DISCUSSION** 

1 Here we have shown how a biophysical principle underlies the emergence of 2 functionally complex 3D developmental structures. Namely, cells increase their 3D 3 connectivity in a logistic-like fashion by means of apico-basal intercalations that require overcoming an energy barrier that grows with the number of 3D neighbors. 4 5 Thus, our analyses explain how the presence of the novel paradigm of epithelial cells' 6 shape and packing, the *scutoid*, affects the cellular connectivity in the third 7 dimension. In that regard, we have shown how the 3D cellular connectivity and tissue energetics are coupled, and we have proposed a quantitative biophysical 8 9 model to explain that relationship.

10 Our biophysical model relies on a phenomenon observed in the Voronoi 11 computational simulations, supported by mathematical arguments, and confirmed in 12 experiments: the "poor get richer" principle (see STAR Methods). Roughly speaking, 13 we have shown that the fewer neighbors a cell has on a surface, the larger is the 14 probability of a 3D cellular connectivity increase. Interestingly, a similar idea has been 15 reported in T1 dynamical processes during the remodeling of planar epithelia where 16 it has been shown that the energy barrier associated with cellular remodeling, rather 17 than being constant, depends on the cellular environment (Bi et al., 2014). Since the 18 scutoidal geometry can be related to planar T1 transitions by exchanging the 19 concepts of space and time, this result reinforces the idea of the existence of 20 universal principles driving the organization of tissues.

21 From the viewpoint of the tissue energetics, both the Voronoi model and in vivo 22 tubes, identify the surface tension energy as the main cause of scutoids appearance 23 and hints at the elastic energy as an additional driver for modulating the propensity 24 of cells to undergo apico-basal intercalations. In that context, our results suggest that 25 the so-called 'bare' transition rate,  $\alpha$ , or even the energy cost required to gain 26 additional neighbors,  $\beta(s)$ , would depend on both contributions. Related to this, 27 previous studies about the role of fluctuations in the remodeling of cellular 28 aggregates have shown that elastic behaviors (opposed to plastic ones) contribute to 29 reduce the cell stress by lowering the energy barrier that cells need to jump over 30 during cellular rearrangements (Marmottant et al., 2009).

1 In our study we have found that in real tissues (both wt and mutant) the value of 2  $\beta(s)$  is larger than in Voronoi models. We hypothesize that it is due to the purely 3 geometrical description used in the latter. In the in silico model the apico-basal intercalations develop as a result of a topological constraint (a Voronoi tessellation) 4 5 that we have shown describes appropriately the geometrical and packing properties 6 of tubular epithelia. However, in the salivary glands, on top of that constraint, the cells must actively remodel their membranes and cytoskeleton to make the 7 8 transitions possible. In that context, the cytoskeleton, adhesion molecules, and 9 cellular membranes are responsible for the biophysical properties of epithelia including their energetics (Gómez-Gálvez et al., 2021b). Thus, to challenge the 10 proposed biophysical model we measured the value of  $\beta(s)$  in salivary glands where 11 12 the amount of the adhesion molecule E-cadh was reduced. Since the 3D connectivity 13 necessarily increases with the surface ratio, the lower effective surface ratio of the 14 mutant gland should correspond with a reduction of the 3D connectivity. However, our results show that wt and mutant glands present the same value of  $\langle n_{3D}(s_h) \rangle$ 15 16 (Table S1, Fig. S7), thus indicating that the decrease of adhesion facilitates the 17 appearance of apico-basal intercalations. In terms of the tissue energetics, these 18 results suggest a reduction of the energy barrier required to undergo apico-basal 19 intercalations in the mutant glands. This prediction was confirmed by the biophysical 20 model that provided a lower  $\beta(s)$  in the mutant case compared with the wt.

21 As for the technical advances associated to our work, we point out that a high level 22 of detail is necessary to quantify the apico-basal intercalation phenomenon and to 23 compare the in vivo data with computational models (Gómez-Gálvez et al., 2021a). 24 Along these lines, the importance of a realistic analysis of 3D cell-cell contacts has 25 been highlighted by recent studies focused on understanding the growth of mouse 26 embryonic lung explants (Gómez et al., 2021) and the early development of C. 27 elegans (Cao et al., 2020) and Ascidians (Guignard et al., 2020). Our novel 28 methodological pipeline (STAR Methods) allows to implement the accurate 3D reconstruction of cells in epithelia subjected to curvature. This analysis makes 29 30 possible to quantify how different packing properties, e.g., intercalations, depend on the apico-basal coordinate. These technical improvements are necessary to extract 31

biological consequences about the cellular and mechanical basis of self-organization
 in curved tissues (Ambrosini et al., 2017; Hirashima and Adachi, 2019; Inoue et al.,

3 2019) or even whole embryos (Shahbazi et al., 2019).

As for the broader implications of our findings, our results provide new biological insight into the regulation of cell-cell connectivity in curved tissues. This property ultimately regulates juxtracrine signaling, and is pivotal for early development, primordia patterning, and cell fate determination (Guignard et al., 2020; Sharma et al., 2019; Tung et al., 2012). Moreover, recent research has shown that cellular connectivity regulates the viscosity of tissues (Petridou et al., 2021).

10 Therefore, our findings open new ways to draw implications about primary 11 developmental processes in which epithelial bending is essential such as 12 tubulogenesis, gastrulation, neurulation, and early embryo development. In addition, 13 we argue that, while our analyses focus on static tissues, our results could also be 14 relevant to understand active 3D tissue remodeling. Dynamic changes of  $\beta(s)$  would 15 modify the apico-basal intercalation propensity and therefore the material-like 16 properties: the larger  $\beta(s)$  the more solid-like the tissue would behave.

17 Recent studies have confirmed that adhesion-dependent active remodeling can be 18 connected to an increased activity of neighbor exchanges. In particular, loss of function mutants of N-cadherin in the presomitic mesoderm of the zebrafish embryo 19 20 cause an increase in extracellular spaces and a solid-fluid jamming transition (Mongera et al., 2018). In addition, it has been recently shown that the stabilization 21 22 of E-cad at the cellular junctions in the Drosophila eye drives an increase of tension that can be transmitted across the tissue (Founounou et al., 2021). This tension 23 24 results in a reinforcement of the solid-like tissue behavior. The salivary glands experiments confirm that a reduction of E-cadherin increases the apico-basal 25 26 intercalation propensity. Our biophysical model predicted that such an increase of 27 the apico-basal intercalation propensity must be correlated with a decrease of the 28 energy barrier  $\beta(s)$ . Notably, this prediction was confirmed through the biophysical 29 analyses of the  $\Delta$ Ecad samples.

Finally, with respect to the applicability of our results to other areas, we expect that the emerging field of organoids will benefit from our discoveries. A precise

1 quantification of the 3D connectivity could then help to understand the lack of 2 reproducibility in organoid production, one of the biggest challenges of the field 3 (Clevers, 2016; Huch et al., 2017; Schutgens et al., 2019). Also, from a medical point 4 of view, it has been recently shown that tissue curvature affects tumor progression due to the imbalance of tensions in apical and basal surfaces of epithelial tubes 5 6 (Messal et al., 2019). Our study explains how cell energetics affect the 3D packing of these cells and therefore may shed light on the mechanism of tumorigenic 7 morphogenesis in tubular organs. 8

9

#### **10 ACKNOWLEDGMENTS**

L.M.E., P.V.-M. and P.G.-G. has been supported by the Ramón y Cajal program 11 12 (PI13/01347); L.M.E., P.V.-M. and P.G.-G. work is funded by the Ministry of Economy, 13 Industry and Competitiveness grant BFU2016-74975-P co-funded by FEDER funds, 14 and by the Spanish Ministry of Science and Innovation Ministry of Science through grant PID2019-103900GB-I00. A.T. is funded by a "Contrato predoctoral PIF" from 15 16 Universidad de Sevilla. L.M.E. and J.A.A.-S. work is funded by the Junta de Andalucía 17 (Consejería de economía, conocimiento, empresas y Universidad) grant PY18-631 co-18 funded by FEDER funds. I.A-C. would like to acknowledge the support of the 2020 19 Leonardo Grant for Researchers and Cultural Creators, BBVA Foundation, and also 20 the University of the Basque Country UPV/EHU grant GIU19/027. S.A. and J.B. have 21 been supported by a Faculty Innovation Grant (FIG) by Lehigh University JB-FIG-2019. J.B. also acknowledges financial support from the Spanish Ministry of Science and 22 23 Innovation through grant PID2019-105566GB-I00 and from the LifeHUB Research 24 Network (CSIC).

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#### 26 DECLARATION OF INTERESTS

- 27 The authors declare no competing interests.
- 28
- 29

#### **1** FIGURE TITLE AND LEGENDS

#### 2 Box

3 A: Scutoids are prismatic-like geometric solids bounded between two surfaces (top and bottom). Scutoids are characterized by three main properties: i) The shape of 4 5 their top and bottom bases, and of every parallel section between them, are 6 polygons. ii) The lateral surfaces of scutoids can be concave and/or convex surfaces such that a set of scutoids can be packed together (laterally) without leaving any 7 8 empty space. iii) Scutoids have at least one vertex along the top-bottom axis such 9 that when packed together there are changes in the nearest-neighbors relationship. 10 The example shows a scheme of a stereotypical scutoid (left) and four scutoids 11 packed together (right).

B: A T1-transition is a tissue rearrangement observed in epithelial surfaces where a
4-cells' motif swaps nearest neighbors along time. T1-transitions enable tissue
plasticity through cellular reorganizations that lead, for example, to elongation in
developing tissues.

16 C: An apico-basal transition, aka an apico-basal intercalation, is a tissue 17 rearrangement along the apico-basal (top-bottom) axis of cells that lead to new 18 cellular contacts (nearest-neighbors exchange). An apico-basal transition is similar to 19 the T1-transition but instead of developing along the time it does along space.

D: A 2D tessellation (aka a 2D mosaic) is a partition of a surface with tiles that do not
overlap or leave any gaps. In this example, the tiles are octagons and squares.

22 E: A 2D Voronoi diagram is a particular type of tessellation built by convex polygons 23 (Voronoi cells). These polygons emerge from a set of generator seeds (black points), 24 such that each cell contains the region that is closer to its generating seed. The so-25 called Lloyd's algorithm makes the seeds of a Voronoi diagram to converge 26 progressively to the centroids (blue points): once a Voronoi diagram is obtained for a set of seeds (black Voronoi diagram,  $V_N$ ), an iteration of the Lloyd's algorithm 27 28 consists in repeating the Voronoi tessellation by replacing the seeds by the centroids 29 of the Voronoi tiles (blue Voronoi diagram,  $V_{N+1}$ ). The Lloyd's algorithm makes the 1 Voronoi diagram progressively more ordered in terms of the polygonal distribution of

2 the Voronoi cells.

F: The surface tension energy is related to the cell-cell adherence through their lateral area contacts. For each cell, the surface tension energy reads,  $E_A = \Lambda A$ , where  $\Lambda$  and A are the effective surface tension parameter and the cellular lateral area respectively. Thus, the average surface tension energy of cells reads  $\langle E_A \rangle = \Lambda \langle A \rangle =$  $E_{\langle A \rangle}$  and is independent of the fluctuations of A.

**G**: The **contractile energy** is related to the polarized cortex activity of epithelia cells at the apical surface. The contractile energy reads  $E_L = \Gamma L^2$ , where *L* stands for the cellular perimeter at the apical surface and  $\Gamma$  is the cortical tension energy per unit of cell apical area. As a result, the average cell apical contractile energy increases with the fluctuations of the apical perimeter:  $\langle E_L \rangle = \Gamma \langle L^2 \rangle = E_{\langle L \rangle} + \Gamma \sigma_L^2$  where  $\sigma_L^2 = \langle L^2 \rangle - \langle L \rangle^2$  is the cellular apical perimeter variance.

14 **H:** The cell **elastic energy** is related to the volume conservation of cells. The cell 15 elastic energy reads,  $E_V = \frac{Y}{2}(V - V_0)^2$ , where Y is proportional to the Young 16 modulus (a quantification of the relationship between the cellular stress and strain) 17 and, V and  $V_0$  represent the *actual* and target cellular volumes respectively. The 18 average elastic energy per cell increases with the fluctuations of the volume: 19  $\langle E_V \rangle = \frac{Y}{2} \langle (V - V_0)^2 \rangle = E_{\langle V \rangle} + \frac{Y}{2} \sigma_V^2$  where  $\sigma_V^2 = \langle V^2 \rangle - \langle V \rangle^2$  is the cellular volume 20 variance.

21

#### **1** Figure 1. *In silico* Voronoi epithelial model: energetics and analysis of apico-basal

#### 2 cell intercalations in tubes

3 A: (left) Scutoids entail apico-basal intercalations among packing cells that can be envisioned as *spatial* T1 transitions to exchange neighbors (right): the green and the 4 5 red cells are neighbors in the basal surface (but not in the apical surface) while the 6 opposite is true for the blue and the yellow cells. B: In silico Voronoi 3D epithelial models are generated by populating with cell seeds (circles) the apical surface,  $\Sigma_{q}$ . 7 The location of cell seeds at any other surface/plane,  $\Sigma$ , is obtained by implementing 8 9 apical normal projections,  $\boldsymbol{n}$ , up to the basal surface,  $\boldsymbol{\Sigma}_{b}$ . At each surface,  $\boldsymbol{\Sigma}$ , a 2D 10 Voronoi tessellation is performed and the 3D cellular shape of the cell is built upon 11 the collection of these tessellations. C: (top) In the particular case of tubular epithelia, normal projections of apical cell seeds correspond to radial projections, and 12 the thickness/curvature of tubes are characterized by the surface ratio,  $s = R/R_a$ 13 (apical/basal surfaces: light/dark blue. R: dashed yellow). (bottom) Illustrative 14 15 rendering of a Voronoi tube cell. D: The so-called CVT scale (iterations of Lloyd's algorithm, STAR Methods) measures the topological disorder in in silico tubular 16 epithelia and leads to different cellular morphologies. In a V1 (Voronoi 1) model cell 17 seeds are randomly distributed on the apical surface to generate a planar Voronoi 18 19 tessellation (STAR Methods). By applying the Lloyd algorithm iteratively, the apical 20 topological disorder diminishes (top to bottom: V1, V5, and V10 examples). The 21 random location of seeds in V1 implies the emergence of a wide range of different 22 polygonal cell types. As Lloyd's algorithm iterates, the larger the tessellation order is (Box E). We observe this progressive ordering from a V1 to V10 as polygonal 23 24 distributions converge to results with a larger proportion of hexagons and a reduction of the other polygonal shapes (inset: polygon distribution insets for V1, V5, 25 and V10). The average number of apico-basal intercalations per cell in in silico tubes 26 (n = 20 realizations per CVT scale, each tube composed by 200 cells) increases with 27 the tissue thickness (surface ratio) but does not change significantly with the CVT 28 29 scale. The black/red/green arrows correspond to the illustrative examples of the 30 planar apical tessellations shown on the left. E: The average lateral cell area as a 31 function of the CVT and the surface ratio (values normalized to the V1 case at  $s_{h} = 10, n = 20$  per CVT scale) indicates that the average surface tension energy 32

does not depend on the level of topological disorder. F: Average (green bar) and 1 2 standard deviation (red lines) of the apical cellular perimeter as a function of the CVT 3 scale. Values normalized with respect to the V1 case (n = 20 per CVT scale). G: The cellular volume variance is a proxy for the average elastic cell energy (STAR 4 Methods). The latter decreases with the CVT scale and increases with the surface 5 ratio (tissue thickness) (n = 20 per CVT scale). Volume values were normalized with 6 7 respect to the V1 case with  $\langle V(s_b = 10) \rangle = 1$ . H: Cross-correlation between average energy profiles along the apico-basal axis,  $\langle E_A \rangle$  (dark grey),  $\langle E_V \rangle$  (red), and  $\langle E_A \rangle$  + 8 9  $\langle E_L \rangle$  (light grey), and the number of apico-basal intercalations,  $\langle i \rangle$ . Solid lines stand for the averages among disorder configurations (i.e., CVT scale) and the dotted lines 10 delimit the standard deviation band.  $\langle E_{\nu} \rangle + \langle E_{\iota} \rangle$  has not been plotted since the extra 11 12 contribution of the contractile term,  $\langle E_L \rangle$ , does not modify the correlation function. I: 13 Cross-correlation between energy gradients  $(\partial_s \langle E_A \rangle$  and  $\partial_s \langle E_V \rangle)$  and the gradient of 14 intercalations along the apico-basal axis  $(\partial_s(i))$ . Color code as in **H**.

### 1 Figure 2. Three-dimensional packing and connectivity properties of the Voronoi

#### 2 tubular model

3 A: (left) Schematic representation of a 3D histogram that accounts for the probability that cells have  $n_a$  (number) of neighbors in the apical surface and  $n_b$  neighbors in the 4 5 basal surface. Cells with the same polygonal class in apical and basal surfaces 6 contribute to bins along the diagonal (red squares). The bins spreading away from 7 the diagonal (green squares) ensures the presence of scutoidal cells. E.g.: the red and 8 green cells shown in the plot contribute to the bins indicated in the 3D histogram 9 (red and green stars respectively). (right) 3D histograms of V5 tubes for increasing values of the surface ratio. A larger value of the spreading coefficient,  $\eta^2$ , (STAR 10 Methods) indicates an increasing number of scutoids. B: Density plot showing the 11 value of the spreading coefficient,  $\eta^2$ , of 3D histograms as a function of the surface 12 ratio and the Voronoi class in *in silico* tubes (n = 20 tubes per CVT scale). C: Cross-13 14 correlation between average energy profiles along the apico-basal axis,  $\langle E_A \rangle$  (dark grey),  $\langle E_V \rangle$  (red), and  $\langle E_A \rangle + \langle E_L \rangle$  (light grey), and the spreading coefficient,  $\eta^2$ . Solid 15 16 lines stand for the averages among disorder configurations (i.e., CVT scale) and the 17 dotted lines delimit the standard deviation band.  $\langle E_V \rangle + \langle E_L \rangle$  has not been plotted since the extra contribution of the contractile term,  $\langle E_L \rangle$ , does not modify the 18 19 correlation function.

#### **1** Figure 3. *Drosophila's* salivary gland analysis

2 A: (top) Full projection of a wildtype salivary gland (cell contours stained by Cy3-3 labeled phalloidin, STAR Methods). (middle) Computer rendering of the segmented 4 salivary gland shown on top. Scale bar  $100\mu m$ . (bottom) 3D rendering of a representative segmented salivary gland. B: Density plot of the 3D distribution of 5 6 neighbor exchanges between apical and basal surfaces as a function of the number of 7 neighbors in apical,  $n_a$ , and basal,  $n_b$ , surfaces (as in Fig. 2A) in wildtype salivary 8 glands (n = 20 glands, 979 cells). C: Average profiles of the number of apico-basal 9 intercalations,  $\langle i \rangle$ , average lateral area,  $\langle A \rangle$ , and cellular volume fluctuations,  $\sigma_v^2$  in in 10 vivo tubes as a function of the apico-basal coordinate, s (n = 20 glands, similar to Fig. 1D-E, G). D-E: Cross-correlation analysis between energy and intercalation 11 profiles (same as Fig. 1H-I). The error band indicates in this case the variability among 12 experimental samples (n = 20 glands). 13

#### 1 Figure 4. Biophysical model: *in silico* and *in vivo* results

2 A: (top) Cell intercalations along the apico-basal axis can be visualized as spatial T1 3 transitions (non-reversible: once a neighbor is won it cannot be lost). (bottom) The "poor get richer" principle (STAR Methods) suggests an increasing energetic cost 4 (i.e., a larger activation energy) for recruiting new neighbors as a function of the 5 6 number of neighbors already won. In our model,  $\beta(s)$  accounts for the energetic cost per 3D neighbor (per apico-basal intercalation) to recruit a new neighbor (STAR 7 Methods). B: The energy landscape shown in B (bottom) can be modeled by a 8 stochastic dynamics (a Kolmogorov rate equation) where cells increase their 3D 9 neighbors with a probability per unit of surface ratio,  $r_{n,m}$ , that depends on the 10 activation energy,  $\beta(s)$ , a 'bare' transition rate,  $\alpha$ , and the maximum cell 11 12 connectivity  $N_{max}$  (STAR Methods). C: Results of the Kolmogorov model in V8  $(s_b = 1.75)$  in silico tubes (n = 20). The left/center density plots represent the 13 cellular connectivity distribution (i.e., the fraction/probability of cells with a given 14 15 number of 3D neighbors) as a function of s obtained in the Voronoi simulation (left) 16 and as predicted by the Kolmogorov model (center); the red circles (left/right) indicate the average number of 3D neighbors per cell  $\langle n_{3D} 
angle$ ; the red line 17 (center/right) shows  $\langle n_{3D} \rangle$  as obtained by the Kolmogorov model. The density plot on 18 19 the right shows the difference between the predicted and the actual connectivity distributions and the corresponding error,  $\varepsilon^2$  (magenta lines). D: Same as panel C but 20 results obtained in salivary glands (n = 20 glands). The maximum value of s in the 21 analyzed radial sections of the glands is s = 6.5. This value being the largest radial 22 23 section of the smallest gland (STAR Methods).

#### **1** Figure 5. Biophysical analysis of ΔEcad salivary glands

2 A: (top) Full projection of a  $\Delta$ Ecad salivary gland (cell contours stained by Cy3-labeled 3 phalloidin, STAR Methods). (bottom) Computer rendering of the mutant salivary gland shown on top. Scale bar  $100\mu m$ . B: Results of the Kolmogorov model for the 4  $\Delta$ Ecad salivary gland (n = 10 glands). The left/center density plots represent the 5 6 connectivity distribution (i.e., the fraction/probability of cells with a given number of 3D neighbors) as a function of s obtained in the Voronoi simulation (left) and as 7 8 predicted by the Kolmogorov model (center); the red circles (left/right) indicate the 9 average number of 3D neighbors per cell  $\langle n_{3D} \rangle$ ; the red line (center/right) shows  $\langle n_{3D} \rangle$  as obtained by the Kolmogorov model. The density plot on the right shows the 10 difference between the predicted and the actual connectivity distributions and the 11 corresponding error,  $\varepsilon^2$  (magenta lines). Same color code than in **Fig 4C-D**. The 12 13 maximum value of s in the analyzed radial sections of the glands is s = 5.5. This 14 value being the largest effective radial section of the smallest gland (STAR Methods). 15 C: Energy cost required to gain additional neighbors as a function of s (STAR **Methods**) for wt glands (green), for  $\Delta$ Ecad glands (red), and for the V8 ( $s_b = 1.75$ ) 16 17 model (blue). The inset shows the values of the bare transition rates,  $\alpha$ , and the 18 average value (along the apico-basal coordinate) of  $\beta$ .

#### **1** STAR METHODS

#### 2 Immunohistochemistry and confocal imaging of salivary glands

3 Flies were grown at 25 °C using standard culture techniques. The following lines 4 were used: Oregon R (wt), UAS-shg-RNAi (BL38207), AB1-Gal4 (BL1824). AB1-Gal4 5 drives Gal4 protein in the third instar larva salivary gland. We dissected the salivary glands from third instar larvae. After PBS dissection, the glands were fixed using 4% 6 7 paraformaldehyde in PBS for 20 min. The samples were washed three times for 10 8 min with PBT (PBS, 0.3% Triton) and then incubated for 1 hr 45 minutes at room 9 temperature with Cy3-labeled phalloidin (Sigma) to label the cell contours of the 10 epithelial cells. Stained larval salivary glands were mounted using Fluoromount-G 11 (Southern Biotech). We used two pieces of double-sided adhesive tape (one on top of each other) as a spacer (Aldaz et al., 2013), so the salivary glands preserve their 12 13 shape. Images were taken using a Nikon Eclipse Ti-E laser scanning confocal 14 microscope. The images were captured using a  $\times 20$  dry objective and 2.5  $\mu$ m steps 15 between slices. The image stacks were exported as 1024 × 1024 pixels TIFF files.

16

#### **17** Quantification of fluorescence intensity

18 The E-cadherin fluorescence intensity was measured in Fiji by using the Plot Profile 19 tool. We used 3 wt and 3  $\Delta$ Ecad representative glands, taking 10 individual 20 measurements for each sample (Fig. S7). We used rectangular ROIs to measure the 21 intensity profiles of lateral cell membrane in the Z-depth where the lumen was 22 visible. In this way, we were able to capture the whole lateral cell membranes from apical to basal. To ensure, a high-quality detection of the cell membrane we 23 24 developed a maximum Z-projection of those Z-slices where the cell outline of interest 25 and the lumen are clearly visible. Note that the output of the Plot Profile is a 2D plot 26 that displays a "column average plot", where the X axis represents the horizontal 27 distance through the selection (apico-basal cell outline) and the Y axis the vertically 28 averaged pixel intensity.

29

#### **1 3D** glands segmentation

2 To segment the salivary gland stacks of images and reconstruct (semi-automatically) 3 the shape of cells in three dimensions we used the Fiji (Schindelin et al., 2012) plugin 4 LimeSeg (Machado et al., 2019). It infers cell outlines by using surface elements 5 ("Surfels") obtained by manually placing single ellipsoidal-like seeds on every cell (see 6 https://imagej.net/LimeSeg for details). Once cell outlines were found, we exported 7 them as point clouds (output). We developed a custom-made Matlab code (2021a 8 MathWorks) to postprocess the output of LimeSeg in order to correct errors and 9 obtain perfectly segmented salivary glands. In addition, we manually segmented the 10 lumen of the glands using the Volume Segmenter app, in Matlab. To faithfully 11 represent the gland as a cylinder, we selected a subset of cells: cells that were not 12 ductal, neither located at the tip of the gland.

13 To segment mutant salivary glands we took advantage from the 20 segmented wt 14 salivary glands, and we used them as training dataset into a deep-learning 15 segmentation pipeline. We trained a stable 3D-U-Net CNN ((Franco-Barranco et al., 16 2021), https://github.com/danifranco/EM Image Segmentation) using as input the 17 salivary glands phalloidin channel (actin filaments) staining cell outlines, and as target the segmented cell outlines. The output (prediction) of this pipeline was a probability 18 19 map of cell outlines, that was post-process using the PlantSeg (Wolny et al., 2020) 20 segmentation module to extract individual instances. Here, again, we segmented the 21 lumen of the glands using the Volume Segmenter app, and segmentation errors were 22 curated using our custom-made Matlab code.

To obtain the cellular neighborhood relations of salivary glands for different values of the radial expansion, we proceeded as follows. We calculated the cell height by estimating the distance between the centroid of the cell apical surface with respect to the centroid position of its basal surface,  $d(s_a, s_b)$ . Then, to capture a concentric radial section of the gland, we linearly extrapolated the equivalent cell height to the given surface ratio, s:

29 
$$d(s_a, s) = d(s_a, s_b) \frac{s}{s_b}$$
(2)

where  $d(s_a, s)$  is the Euclidean distance between the position of the centroid of the cell at the apical surface,  $s_a = 1$ , and the position of the centroid at a value  $s = R/R_a$  of the radial expansion. Finally, to obtain the gland cylindrical radial section for a given value of the radial expansion, s, we collected all voxels between apical and the upper bound of the calculated distance  $d(s_a, s)$ .

6

#### 7 Salivary glands measurements

8 We quantified the following geometrical and topological/connectivity descriptors of 9 the segmented salivary glands using a custom-made Matlab code:

10 - Surface ratio (s): Assuming a cylindrical shape for glands, we estimated s by 11 measuring the minimum distance between each cell apical centroid and lumen skeleton ( $R_a$ ), and measuring h, the distance between apical cell 12 13 centroid and cell centroid of an outer cell layer (i.e., basal surface or a concentric layer between apical and basal). Being, the individual surface ratio 14 of a cell,  $s_{cell} = \frac{R_{a_{cell}} + h_{cell}}{R_{a_{cell}}}$ , we averaged all the individual cell measurements 15 to calculate the representative s value corresponding to a gland,  $s = \langle s_{cell} \rangle$ . 16 17 - Cell apical perimeter, lateral surface area, and the cellular volume.

18- Number of cell contacts: we measured the number of cell neighbors of each19cell surface, that is, apical, basal or lateral. In order to remove artefacts, 220cells must share at least 0.5% of their lateral surfaces area to enable them to21be considered as neighbors.  $n_a$ ,  $n_b$ , and  $n_{3D}$  of each gland were calculated22after averaging the number of cells neighbors along the gland.

Percentage of scutoids, average of apico-basal transitions. We quantify the
 percentage of scutoidal cells that conform the gland and the number of apico basal transitions in which each cell is involved.

26

All the measurements were carried along different concentric radial sections of the glands. We captured the gland thicknesses starting at the apical surface ( $s_a = 1$ ) and increasing progressively the surface ratio by  $\Delta s = 0.5$ , until reaching the basal surface ( $s_b$ ). In this way, the number of the captured radial sections will depend on

the  $s_b$  value of each gland. To compare the glands of each phenotype (either wt or mutant) in terms of connectivity related with the surface ratio, we used a maximum radial section common to all the glands.

In  $\Delta$ Ecad mutant glands, due to their phenotype (cells bulge at the basal surface), we removed the bulging tips of cells to quantify the *effective* surface ratio  $s^*$ : the maximum value of the surface ratio up to which cells are contacting (that is,  $1 \le s \le s^* \le s_b$ ). We noticed that the 3D connectivity of cells is not modified by this approach. To remove the volume of cell tips, we captured all lateral and apical surfaces of cells and we filled each cell volume using the *alphaShape* Matlab function.

10

#### 11 Voronoi tubular model

12 Using custom-made Matlab code we generated a Voronoi model that simulates the 13 surface of a cylinder unfolded over the Cartesian plane, see details in Gomez-Galvez et al. ((Gómez-Gálvez et al., 2018), Methods). The only difference with the cited 14 15 methodology, is that in this work the Voronoi diagrams has been constructed by 16 means of the Delaunay triangulation technique. Therefore, we just considered the 17 cells' vertices information (Cartesian coordinates and connections) for a much faster computation. For each realization, we used an initial set of 200 randomly located 18 19 seeds on a rectangular domain of 512 (X axis; transverse axis of cylinder) per 4096 (Y axis; longitudinal axis of cylinder). We performed this procedure for 10 different 20 21 initial Voronoi diagrams (Voronoi 1 (V1, random seeds) to Voronoi 10 (V10, more 22 ordered and homogeneous cells). These diagrams represent the apical (inner) 23 surfaces of computational tubes, and they were obtained by applying N-1 times the 24 Lloyd's algorithm (Lloyd, 1982) to the random seeds, where N is then the resulting 25 Voronoi model. For instance, to compute a V1, we use purely random seeds, while to 26 obtain a V4 diagram, it would be required to apply 3 times the Lloyd's algorithm to 27 random seeds. In the limit of the CVT scale (iterations of the Lloyd's algorithm) going 28 to infinity the organization of cells tends to a hexagonal lattice. Subsequent radial 29 sections that define computational tubes with different surface ratios were obtained 30 by implementing a radial projection of the Voronoi seeds. For each apical surface of 31 the tube, we generated 40 expansions by incrementing the surface ratios  $(s_h)$  using

0.25 steps: 1 (apical), 1.25, 1.5, ..., 10 (19 s-steps × 10 apical cell arrangements × 20
 realizations).

3 As for the 3D reconstruction of cells in Voronoi tubes, each set of seeds that 4 characterizes cells on a given cylindrical section defines a unique 2D Voronoi diagram at every surface and hence the corresponding 2D cellular domains. The set of 2D 5 6 Voronoi regions that belong to the same radially projected seed from the apical to 7 the basal surface then define each 3D cellular shape. Each of the obtained 3D cells 8 was further processed using the Matlab function 'alphaShape' to transform the set of 9 voxels into a compact, solid, object. This reconstruction pipeline was implemented using Matlab (2021a). 10

As for the connection of the CVT scale with the average elastic energy of cells, we 11 12 first notice that for a given tube of length L, radiuses R and  $R_a$ , and with a fixed 13 number of cells, N, the average cell volume,  $\langle V \rangle$ , is independent of the CVT scale:  $\langle V \rangle = \frac{1}{N} \sum_{i=1}^{N} V_i = \pi L (R^2 - R_a^2) / N = \pi L R_a^2 (s^2 - 1) / N$ . On the other hand, if cells 14 have a target volume  $V_0$  then the elastic energy (linear regime) of cell *i* reads 15  $E_{V_i} = \frac{Y}{2} (V_i - V_0)^2$ , where Y is proportional to the Young's modulus. Consequently, 16 the average cell elastic energy,  $\langle E_V \rangle = \frac{1}{N} \sum_{i=1}^N E_{V_i} = E_{\langle V \rangle} + \frac{Y}{2} \sigma_V^2$ , where  $E_{\langle V \rangle} = E_{\langle V \rangle}$ 17  $\frac{Y}{2}(\langle V \rangle - V_0)^2$  is the elastic energy of a cell with an average cell volume  $\langle V \rangle$  and 18  $\sigma_V^2 = \langle V^2 \rangle - \langle V \rangle^2$  is the variance of the cellular volume (the cell size fluctuations). 19 Since  $E_{(V)}$  is independent of the CVT scale and  $\sigma_V^2$  decreases with the CVT scale (i.e., 20 21 as the tissue becomes more ordered) then the average elastic cell energy necessarily 22 decreases as the CVT increases. In our simulations and experiments the cellular volume is computed by using the value of cell area sections  $\mathcal{A}(s)$  as a function of the 23 surface ratio, s. Specifically, we used the trapezoidal rule,  $V(s) = \int_{z=s_a}^{z=s} \mathcal{A}(z) dz \approx$ 24  $\frac{\Delta s}{2} \left[ \mathcal{A}(s_a) + 2\mathcal{A}(s_a + \Delta s) + \dots + 2\mathcal{A}(s_a + (n-1)\Delta s) + \mathcal{A}(s_a + n\Delta s) \right].$ 25 Where  $s_a + n\Delta s = s$  and  $\Delta s = 0.25$ . Cell volumes where normalized considering Voronoi 1 26 27 tubes from CVT scale as reference, such its average cell volume will represent the unity  $\langle V(s_b = 10) \rangle = 1$ . Likewise, for estimating the surface lateral area we used the 28 29 trapezoidal rule using the value of the cellular perimeter, L(s), that is: A(s) =

$$1 \qquad \int_{z=s_a}^{z=s} L(z) \ dz \approx \frac{\Delta s}{2} [L(s_a) + 2L(s_a + \Delta s) + \dots + 2L(s_a + (n-1)\Delta s) + L(s_a + \Delta s)]$$

2  $n\Delta s$ )]. Besides, we normalized the lateral surface area following the same criterion 3 than with volumes. Additionally, we proceed in a similar way to estimate the cellular 4 lateral area and volume as a function of *s* in salivary glands.

5

#### 6 Cross-correlation definition

7 Dimensionless cross-correlation, C(s), between X(s) (e.g.  $\langle E_A(s) \rangle$ )and Y(s) (e.g. 8  $Y(s) = \langle i(s) \rangle$ ) is defined as follows:  $C(s) = \frac{1}{N} \sum_{S'} X(s') Y(s + s')$  where N =9  $(\sum_{S'} X(s')^2 \sum_{S''} Y(s'')^2)^{1/2}$  is a normalization constant such that the auto-10 correlation becomes one (at maximum) at zero lag. When required, spatial 11 derivatives were estimated as  $\partial_s F(s) = \frac{F(s + \Delta s) - F(s)}{\Delta s}$ .

12

#### 13 Voronoi tubular model measurements.

We measured the following properties of cells in Voronoi tubular models: area, perimeter and number of sides of cells for a given radial section, and total number neighbors. Additionally, we computed the percentage of scutoids, the number of apico-basal transitions, the polygon distribution of every surface (radial sections). In these quantifications, we disregarded cells at the boundaries (tips of tubes) to avoid 'border effects'.

20

### 21 Relation between total accumulated 3D neighbors and the number of 22 intercalation events

Scutoids have a Euler characteristic  $\chi = 2$  such that V - E + F = 2, where V, E, and F accounts for the number of vertexes, edges, and faces respectively. We assumed that the apical, a, and basal, b, faces of scutoids tessellating a cylindrical space have radial coordinates  $R_a$  and  $R_b$  respectively. Then, for any value of the surface ratio expansion,  $s = R/R_a$ , these solids can be mapped into a connected plane graph with the same Euler characteristic (a sort of projection of the vertexes and connectors into the plane, see **Fig. S10.** Thus, as a function of s, the accumulated

1 number of 3D neighbors reads  $n_{3D}(s) = E(s) - V(s)$ . Since in tubular geometries 2 the radially projected seeds from the apical to the basal surface never come closer, 3 as *s* increases (i.e., apico-basal intercalations are not reversible).

$$n_{3D}(s) = max(\{V(s)\}) = min(\{V(s)\}) + i(s)$$
(3)

5 where  $\{V(s)\} = \{V(1), V(1 + ds), \dots, V(s_b)\}$  and i(s) denotes the number of 6 intercalation points in the interval  $s \in [1, s_b]$ . In the case of a 3D tessellation with N7 cells, where M of them do not show any intercalation, the total number of 8 accumulated neighbors reads,

10

4

$$n_{3D}(s) = \sum_{j=1}^{N} n_{3D}^{(j)}(s) = \sum_{j=1}^{M} V^{(j)}(1) + \sum_{j=1}^{N-M} max(\{V^{(j)}(s)\}) = \sum_{j=1}^{M} V^{(j)}(1) + \sum_{j=1}^{N-M} \{min(\{V^{(j)}(s)\}) + i^{(j)}(s)\}$$
(4)

Given that each intercalation point is shared by four cells, two of them necessarily increase their number of vertices in a given *s*-plane and two of them decrease their number of vertices. Thus, in the case of a decrease  $max(\{V^{(j)}(s)\}) = V^{(j)}(1)$  and in the case of an increase  $min(\{V^{(j)}(s)\}) + i^{(j)}(s) = V^{(j)}(1) + i^{(j)}(s)$ . Consequently,

15 
$$n_{3D}(s) = \sum_{j=1}^{N} V^{(j)}(1) + \sum_{j=1}^{(N-M)/2} i^{(j)}(s) = \sum_{j=1}^{N} V^{(j)}(1) + \frac{1}{2} \sum_{j=1}^{N-M} i^{(j)}(s)$$
 (5)

16 where we used the fact that for every intercalation event that increases by one the number of neighbors there is one that decreases the number of neighbors in the 17 same amount; consequently, we can add up all intercalation events and divide by 18 two. Hence the average number of accumulated 3D neighbors,  $\langle n_{3D}(s) \rangle = n_{3D}(s)/N$ 19 reads  $\langle n_{3D}(s) \rangle = \langle V(1) \rangle + \langle i(s) \rangle /2; \langle i(s) \rangle$  being the average number of apico-basal 20 21 intercalations per cell. Finally, by considering that any s-surface, and in particular the 22 apical surface s = 1, corresponds to a 2D tessellation of convex polygons,  $\langle V(1) \rangle = 6$ we conclude that, 23

24

$$\langle n_{3D}(s)\rangle = 6 + \frac{1}{2}\langle i(s)\rangle \tag{6}$$

25

## 26 The 3D neighbor's accumulation in tubular epithelia follows a "poor get richer"27 principle

In order to investigate additional phenomena that could help to understand how the 3D cellular connectivity is regulated, we computed the net gain of cellular 1 neighbors in epithelial tubes as a function of the 2D polygonal cell class at the apical 2 surface. We observed, both in the salivary glands and in the Voronoi model (in 3 particular in the case V8 ( $s_b = 1.75$ ) that compares the best with *in vivo* glands), that the smaller the number of neighbors of a cell at the apical surface, the larger the net 4 5 gain of 3D cellular contacts (Fig. S4). This behavior was also obtained with respect to 6 the 2D polygonal cell class at the basal surface (Fig. S4). These results suggest that, in terms of the cellular packing, tubular epithelia follow a "poor get richer" principle: 7 the less neighbors a cell has in a surface (apical or basal), the larger the net increase 8 9 of 3D cellular contacts.

10

#### 11 In Voronoi tubes the net gain of 3D neighbors is bounded

12 The "poor get richer" behavior can be justified by mathematical arguments that 13 show that the probability to increase the cellular connectivity necessarily decreases 14 with the number of current neighbors (Fig. S5). Assuming a cylindrical geometry (e.g., 15 epithelial tubes), each point at a given radial surface can be represented into the 16 Cartesian plane; where coordinate x accounts for the cylindrical transversal 17 coordinate and coordinate y for the longitudinal one (see Fig. S5). Thus, if the 18 coordinates of a point (e.g., a Voronoi seed) at the apical surface are given by (x, y), the coordinates of that point at a surface with a value of the cylindrical radial 19 expansion  $s \in [1, \infty)$  can be found by defining the function  $f_s: \mathbb{R}^2 \to \mathbb{R}^2$   $f_s(x, y) =$ 20 (sx, y). Under these conditions, we aim to characterize the seeds that generate 21 22 scutoids (exchanges in the neighboring relations of seeds) as *s* changes.

*Lemma 1.* Given three non–colinear points  $\{A, B, C\}$  that define a circle (a nearestneighbors relation), and another exterior point D, if s > 1 exists such that  $f_s(D)$  is interior to the circle defined by  $\{f_s(A), f_s(B), f_s(C)\}$ , then D is inside of the vertical parabola containing  $\{A, B, C\}$  (**Fig. S5**).

27 *Remark.* If two of the three points  $\{A, B, C\}$  are on the same vertical line, then the 28 parabola considered in Lemma 1 degenerates as a vertical strip. Even in this case, the 29 thesis of the Lemma is true if we replace the interior of the parabola by the inside of 30 the strip.

1 *Proof.* Without loss of generality, we can suppose that  $\{A, B, C\}$  are 2 counterclockwise oriented and that they have Cartesian coordinates  $(a_1, a_2)$ , 3  $(b_1, b_2)$  and  $(c_1, c_2)$  respectively.

Thus, the point D(x, y) is outside the circle defined by  $\{A, B, C\}$  if, and only if, the sign of the following determinant is negative:

8

 $\begin{vmatrix} a_1 & a_2 & a_1^2 + a_2^2 & 1 \\ b_1 & b_2 & b_1^2 + b_2^2 & 1 \\ c_1 & c_2 & c_1^2 + c_2^2 & 1 \\ x & y & x^2 + y^2 & 1 \end{vmatrix} = \begin{vmatrix} a_1 & a_2 & a_1^2 & 1 \\ b_1 & b_2 & b_1^2 & 1 \\ c_1 & c_2 & c_1^2 & 1 \\ x & y & x^2 & 1 \end{vmatrix} + \begin{vmatrix} a_1 & a_2 & a_2^2 & 1 \\ b_1 & b_2 & b_2^2 & 1 \\ c_1 & c_2 & c_2^2 & 1 \\ x & y & y^2 & 1 \end{vmatrix} < 0$ (7)

7 For the sake of simplicity, we represent the previous equation as:

$$det(\mathcal{A}) = det(\mathcal{B}) + det(\mathcal{C}) < 0 \tag{8}$$

9 On the other hand, by considering x and y as variables, the equation  $det(\mathcal{A}) = 0$ 10 corresponds to the circle defined by  $\{A, B, C\}$ , and  $det(\mathcal{B}) = 0$  corresponds to the 11 vertical parabola defined by the same three points. Consequently, the inequality 12  $det(\mathcal{B}) > 0$  defines the locus of interior points to that parabola.

Now, assuming that s > 1 exists such that  $f_s(D)$  is interior to the circle defined by  $\{f_s(A), f_s(B), f_s(C)\}$ . Then,

$$\begin{vmatrix} sa_1 & a_2 & s^2a_1^2 + a_2^2 & 1 \\ sb_1 & b_2 & s^2b_1^2 + b_2^2 & 1 \\ sc_1 & c_2 & s^2c_1^2 + c_2^2 & 1 \\ sx & y & s^2x^2 + y^2 & 1 \end{vmatrix} = s^3 det(\mathcal{B}) + s det(\mathcal{C}) > 0$$
(9)

15 Or, equivalently,  $s^2 det(\mathcal{B}) + det(\mathcal{C}) > 0$ , so,  $s^2 det(\mathcal{B}) > -det(\mathcal{C})$ . If  $det(\mathcal{B}) <$ 16 0, then  $1 < s^2 < -\frac{det(\mathcal{C})}{det(\mathcal{B})}$  and therefore  $det(\mathcal{B}) > -det(\mathcal{C})$ . The latter is in 17 contradiction with  $det(\mathcal{B}) + det(\mathcal{C}) < 0$ . As a result,  $det(\mathcal{B}) > 0$ , and the following 18 inequality holds,

$$s^{2} > -\frac{\det(\mathcal{C})}{\det(\mathcal{B})} > 1 \tag{10}$$

19 Notice that if the circle defined by  $\{A, B, C\}$  is surrounded by a set of points and we 20 change continuously the parameter *s* in the interval  $[1, \infty)$ , it is possible to detect the 21 first point touching the circle defined by  $\{f_s(A), f_s(B), f_s(C)\}$ . That point can be 1 obtained by computing all the points at  $s = \sqrt{-\frac{det(C)}{det(B)}}$ . Hence, the first point 2 contacting the circle will be that with the minimum value of s.

As for proving that the average of the number of neighbors of a cell induced by a seed grows is bounded as a function of the surface ratio, we state the following proposition:

6 Proposition 1. Given a Voronoi seed representing a cell, if  $n_{3D}(s)$  is the total 7 number of accumulated cell neighbors as s increases from s = 1 (apical surface) to a 8 given value of s, then  $\langle n_{3D}(s) \rangle$  is a bounded function for a finite cylinder.

9

10 *Proof.* We model the apical surface as the cylinder  $2\pi r \times h$ , where r representes the inner radius and h the length of the cylinder. Given a seed A in that surface, in the 11 12 corresponding Delaunay triangulation it appears as a point surrounded by triangles 13 defining the neighborhood of A. By Lemma 1, each triangle defines a vertical 14 parabola and a circle. So, any other seed touching A in other layer must be inside of 15 one of the parabolas and outside of all circles (see Fig. S5). Let's denote  $\mathcal{R}_{s,A}$  the 16 feasible region for a new neighbor of A in the layer represented by s, i.e., all points inside one of the parabolas and outside all the circles. Thus, if  $\#(\mathcal{R}_{SA})$  is the number 17 of seeds in that region that are not neighbors of A in the apical surface, obviously, an 18 19 upper bound to the number of new neighbors to A is given by  $\#(\mathcal{R}_{s,A}) \leq \#(\mathcal{R}_{1,A})$ . 20

On the other hand, that number of seeds is, in average, proportional to the density of seeds times the area of  $\mathcal{R}_{s,A}$ , therefore, the average number of accumulated neighbors of A, denoted as  $\langle n_{3D}(A) \rangle$ , will be bounded by the change of the density of points when growing s, this is to say,

25

$$d\langle n_{3D}(A)\rangle \le M \cdot \frac{\mathcal{R}_{s,A}}{2\pi sr \cdot h} ds \tag{11}$$

where *M* represents the total number of seeds (i.e., the total number of cells that is a constant) and the quotient is the area of  $\mathcal{R}_{s,A}$  divided by the area of a given radial layer. In general, it is not possible to integrate equation (4), since the area of  $\mathcal{R}_{s,A}$  is known only in very few, particular, cases.

1 In the case of a finite cylinder,  $(n_{3D}(A)) \le \#(\mathcal{R}_{s,A}) \le \#(\mathcal{R}_{1,A})$  leads, summing up to

2 all the seeds and dividing by *M*, to the upper bound

3 
$$\langle n_{3D}(s) \rangle \leq \frac{1}{M} \cdot \sum_{A} \#(\mathcal{R}_{1,A})$$
 (12)

4 thus,  $\langle n_{3D}(s) \rangle$  is necessarily a bounded function. This expression indicates that the 5 number of new neighbors when increasing *s* exhausts since the number of cells is a 6 resource shared by all the layers. It is possible to obtain an upper bound to 7  $N_{max} = \lim_{s \to \infty} \langle n_{3D}(s) \rangle$  since, after a flip in the Delaunay triangulation, the edge 8 disappearing (i.e., a cell contact loss) can never be recovered in a cylindrical 9 geometry. Thus,  $M \cdot (N_{max} - n_{3D}(1))$  is bounded by the number of edges that 10 complement the original Delaunay triangulation on the apical surface, that is,

11 
$$N_{max} - \langle n_{3D}(1) \rangle \le \frac{1}{M} \cdot \left( \frac{M(M-1)}{2} - M \frac{\langle n_{3D}(1) \rangle}{2} \right) = \frac{M-1}{2} - \frac{\langle n_{3D}(1) \rangle}{2}$$
(13)

12 leading to

13 
$$N_{max} \le \frac{M-1}{2} + \frac{\langle n_{3D}(1) \rangle}{2} \le \frac{M-1}{2} + 3 = \frac{M+5}{2} (14)$$

14 Where we have assumed that  $\langle n_{3D}(1) \rangle = 6$ . The simulations of the computational 15 Voronoi model and the data of the salivary gland show that  $N_{max}$  is in fact much 16 smaller that the theoretical bound  $\frac{M+5}{2}$ .

17

#### **18** A Kolmogorov rate equation for the 3D cellular connectivity

The equation for how the probability,  $P_m$ , of having m accumulated 3D neighbors (i.e.,  $m = n_{3D}$ ) changes as the surface ratio (apico-basal dimensionless radial coordinate) increases from s to s + ds can be described by the following Markov equation (Fig. 4A-B),

23 
$$P_m(s+ds) = P_m(s)T_{m,m} + P_{m-1}(s)T_{m-1,m}$$
(15)

where  $T_{n,m}$  is the probability of changing the number of neighbors from n to m due to an apico-basal intercalation. Since  $\sum_m T_{n,m} = 1$  (normalization of the transition probabilities) and  $T_{n,m} = f(n,m) \{\delta_{n-1,m} + \delta_{n,m+1}\}$  (each intercalation can only possibly induce to win one neighbor) then  $T_{m,m} = 1 - T_{m,m+1}$  and the above Markov equation can be written as a Kolmogorov equation (a.k.a. Master equation):

$$\frac{dP_m(s)}{ds} = P_{m-1}(s)r_{m-1,m} - P_m(s)r_{m,m+1}$$
(16)

where  $r_{n,m}$  accounts for the probability of apico-basal intercalations per unit of surface ratio, i.e.,  $T_{n,m} = r_{n,m}ds$ . We point out that our model accounts for apicobasal intercalations that occur due to curvature effects such that  $s = R/R_a$  changes along the apico-basal coordinate of cells (i.e., bending, folding). Thus, our model does not capture the apico-basal intercalations that develop due to active cellular processes (e.g. cellular extrusion, cell divisions) either in bended tissues or in the case of tissue planar geometries.

9 By following the Eyring model (Eyring, 1935), i.e., if we assume an Arrhenius-like kinetics such that to win neighbors there is an energy cost (see (Bi et al., 2014)) then 10  $r_{m,m+1} = \hat{\alpha} e^{-\Delta E_m}$ , where  $\hat{\alpha}$  is the so-called pre-exponential factor that modulates 11 the "bare" frequency of intercalations (per unit of surface ratio expansion, s) and 12  $\Delta E_m$  is a dimensionless activation energy (in units of the effective thermal energy 13 14 associated with membrane fluctuations  $\xi$  (Marmottant et al., 2009). The observed "poor get richer" behavior suggests that the activation energy,  $\Delta E_m$ , increases with 15 m. This can be explained as a result of a cumulative process if we assume that each 16 17 neighbor that is gained implies to overcome an energy barrier,  $\beta(s)$ , through an apico-basal intercalation. Consequently,  $e^{-\Delta E_m} = \prod_{n=1}^{n=m} e^{-\beta(s)} = e^{-m \cdot \beta(s)}$ . Thus, 18 19  $\beta(s)$  represents the dimensionless activation energy of a cell per 3D neighbor or, in the context of the different energetic contributions reviewed in this manuscript, to 20 the energy barrier required to perform a spatial T1-transition following a surface 21 energy minimization process (Gómez-Gálvez et al., 2018; Mughal et al., 2018). As for 22 23 the dependence of  $\beta$  on s, the simplest mathematical form that recapitulates the fact 24 that the apical and basal surfaces accumulate more cell-cell adherent complexes (either in wt or mutant phenotypes) is quadratic (Fig. S7):  $\beta(s) = \beta_0 \left(1 + \beta_0 \right)$ 25  $\frac{\delta}{2}(s-s_0)^2$ ). The average, along the apico-basal coordinate, of the energy cost then 26 reads  $\bar{\beta} = 1/(s_b - 1) \int_1^{s_b} \beta(s) \, ds$ . On the other hand, the mathematical calculations 27 indicate that the intercalation rate  $r_{m,m+1}$  becomes null for a finite value of m or, 28 alternatively, that the activation energy becomes infinite for a finite value of m. 29 30 Otherwise, the net gain of new neighbors is not bounded. This fact can be accounted

for by assuming that the bare frequency is a function of the number of neighbors,  $\hat{\alpha} = \hat{\alpha}(m)$ , such that  $\frac{d\hat{\alpha}}{dm} < 0$  and becomes null for a finite value of m. For the sake of simplicity, we assume that up to first order in m:  $\hat{\alpha} = \alpha(N_{max} - m)$ , where  $N_{max}$  is the asymptotic, maximum, number of 3D neighbors a cell can possibly have. Summarizing, the apico-basal intercalation rate  $r_{m,m+1}$  reads,

12

$$r_{m,m+1} = \alpha (N_{max} - m)e^{-m\beta(s)}$$
 (17)

7 Under these conditions, the Kolmogorov equation reads,

8 
$$\frac{dP_m(s)}{ds} = \alpha \left( N_{max} - (m-1) \right) e^{-\beta(s)(m-1)} P_{m-1}(s) - \alpha (N_{max} - m) e^{-\beta(s)m} P_m(s)$$
9 (18)

10 On the other hand, the equation satisfied by the average number of accumulated 11 3D neighbors,  $\langle n_{3D} \rangle = \langle m \rangle$ , reads,

$$\frac{d\langle m(s)\rangle}{ds} = \sum_{m} m \frac{dP_m(s)}{ds} = \sum_{m} r_{m,m+1} P_m(s) = \langle r_{m,m+1} \rangle$$
(19)

13 We notice that this equation implies an important role of the disorder (i.e. the distribution  $P_m$ ): even in conditions under which the transition rate,  $r_{m,m+1}$ , is 14 "large", the resulting growth of 3D neighbors,  $\frac{d\langle m(s)\rangle}{ds}$ , and, consequently, the net 15 16 accumulation of 3D neighbors, can be more prominent in conditions where the 17 transition rate is "small". To illustrate this effect, we consider the following example. For the sake of simplicity, we evaluate the initial growth of 3D neighbors starting 18 19 from the apical surface, i.e. we particularize Eq. (19) to the case s = 1 (and hence according to Euler's formula  $\langle P_m(1) \rangle = \sum_m m P_m(1) = 6$ ) and consider two possible 20 conditions: a fully ordered (o) distribution with  $P^o_m=\delta_{m,6}$  (i.e., all hexagons) and a 21 disordered (d) condition that combines with equal probability cells with 3, 6, and 9 22 sides in the apical surface, i.e.  $P_m^d = \frac{1}{3} (\delta_{m,3} + \delta_{m,6} + \delta_{m,9})$ . We also assume that 23  $\beta(s)\simeq \bar{\beta}$  (i.e., we approximate the energy cost to gain new 3D neighbors by its 24 average) and that  $\bar{\beta}^o < \bar{\beta}^d$ , and also that  $\alpha^o < \alpha^d$  (Fig. S9). Under these conditions, 25 for the same  $N_{max}$ , the following holds,  $r_{m,m+1}^{o} > r_{m,m+1}^{d}$ , that is, the transition rate 26 27 to gain new 3D neighbors is larger in the ordered case than in the disorder case. This is in fact the situation that we observed in the Voronoi tubular model when we 28

1 estimated the value of the energy barrier to gain new neighbors:  $\alpha$  and  $\beta(s)$ 2 decrease as the CVT scale increases even though the surface tension energy is independent of the CVT scale (see Fig. S9, Fig. 1, and Table S1). However, it is 3 possible to find large regions in terms of the values of  $\bar{\beta}^o$ ,  $\bar{\beta}^d$ ,  $\alpha^o$ , and  $\alpha^d$  where 4  $\frac{d\langle m(1)\rangle}{ds}\Big|_{d} > \frac{d\langle m(1)\rangle}{ds}\Big|_{o}$  (Fig. S11). That is, the growth of 3D neighbors starting from the 5 6 apical surface (i.e. s = 1) in the disorder case can be actually larger than that of the 7 order case despite the fact that the transition rate to gain new 3D neighbors is smaller in the former. 8

9 Also, from Eq. (19), it is possible to infer, approximately, the expected behavior of
 (m(s)) = (n<sub>3D</sub>(s)) as follows. First, by performing a mean-field-like approximation,
 i.e., (F(m)) ≈ F((m)),

12 
$$\frac{d\langle m \rangle}{ds} \approx \alpha (N_{max} - \langle m \rangle) e^{-\beta(s)\langle m \rangle}$$
(20)

13 Second, assuming that  $\beta(s) < 1$  (otherwise it is difficult to justify the observed 14 presence of apico-basal intercalations),

15 
$$\frac{d\langle m \rangle}{ds} \approx \alpha (N_{max} - \langle m \rangle) (1 - \beta(s)\langle m \rangle) + \mathcal{O}(\beta^2)$$
(21)

16 Eq. (21) is formally a logistic-like growth equation that can solved subjected to the 17 condition  $\langle m(1) \rangle = 6$  (the average number of neighbors in the apical surface is 6).

We notice that in this case, the disorder levels of the wt and the mutant glands are similar. Consequently, the accumulation of 3D neighbors only depends on the transition rates,  $r_{m,m+1}$ , that in turn are larger in the mutant background since the energy barrier decreases.

For finding the parameters of the Kolmogorov model, Eq. (19), that better fit *in silico* tubes and salivary glands we implemented an algorithm that solves, numerically, the set of equations defined by Eq. (19) and the normalization condition  $\sum_{m=1}^{\infty} P_m(s) = 1$ to obtain  $\langle m(s) \rangle = \sum_m m P_m(s)$ . Such algorithm minimizes the error between the curves  $\langle m(s) \rangle$  obtained in the model and in experiments.

The values of the parameters obtained were further used to compare the predicted probability distribution of having m accumulated 3D neighbors for a given value of s:  $\{P_m(s)\}$ . We evaluated the relative error of this prediction with respect to the actual 1 distribution from data,  $P_m^{actual}(s)$ , by computing  $\varepsilon^2 = \frac{1}{2} \sum_m \left( P_m^{actual}(s) - P_m(s) \right)^2$ . 2 This quantity is normalized such that in case of the following situation of full 3 disagreement between the distributions,  $P_m^{actual}(s) = \delta_{m,i}$  and  $P_m(s) = \delta_{m,j}$  with

4  $i \neq j$ , provides  $\varepsilon^2 = 1$  (i.e., 100% error).

5

# Quantitative characterization of spreading in neighbor exchange distributions between apical and basal surfaces

8 In order to characterize the spreading away from the diagonal in the neighbor 9 exchange distributions between apical and basal surfaces, e.g., Fig. 2A, we followed 10 the same approach used to quantify intrinsic noise during gene expression processes,  $\eta^2 = \frac{\langle (n_a - n_b)^2 \rangle}{2 \langle n_a \rangle \langle n_b \rangle}$ Thus, 11 see (Elowitz, 2002). where  $\langle z(n_a,n_b)\rangle = \sum_{n_a,n_b} z(n_a,n_b) p(n_a,n_b); \; z \; {\rm representing \; any \; function \; of \; } n_a \; {\rm and \; } n_b$ 12 and  $p(n_a, n_b)$  being the probability of neighbor exchange events. We point out that 13 bins in the diagonal do not correspond necessarily to prismatic cells since a fraction 14 15 of cells can conserved the polygonal class in apical and basal surfaces and yet 16 undergo apico-basal intercalations.

17

#### **18** Statistical comparisons

19 The characteristics extracted from wildtype and mutant glands were compared by using a univariate statistical protocol (Table S1). This procedure allows to study if the 20 21 data from two different groups of data follow a similar distribution: 1) we evaluated 22 whether features values of these two kinds of glands presented normal distribution 23 and similar variance using the Shapiro-wilk test and two-sample F-test respectively. 24 2) If data followed a normal distribution and had similar variance, we employed the 25 two-tailed Student's t-test. 3) In case, data presented a normal distribution but not 26 equal variance we employed the two-tailed Welch test to compare means from both 27 groups. 4) When data did not present normal distribution, we used the Wilcoxon test 28 to compare medians from both groups.

In a different statistical analysis, we tested polygon distribution similarity from apical and basal surfaces of wildtype and mutant glands and V8 at  $s_a = 1$ ,  $s_b = 1.75$ 

- 1 and  $s_b = 10$  (**Table S1**). Following the guidelines from (Sánchez-Gutiérrez et al.,
- 2 2016), we implemented chi-squared tests across all samples, being corrected for
- 3 multiple testing using the method of Benjamini and Hochberg. To develop a more
- 4 robust analysis, we used the distribution of 5-, 6- and 7-sided polygons due to the
- 5 low presence (or inexistence) of the other kind of polygons (3-, 4-, 8-, 9-sided cells).
- 6

#### 7 Data and code availability

- 8 All the necessary materials to reproduce this study are available at Mendeley Data
- 9 repository: DOI: 10.17632/gpz68wzhc2.1 and https://osf.io/nd5t6/.

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